

# **Photogrammetry II**

## **Introduction**

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# Module: Photogrammetry

Photogrammetry I (summer term)

- 3h VL + 2h Ü

Photogrammetry II (winter term)

- 2h VL + 1h Ü + 1h T
- **Exam:** at the end of the winter term

# Expected Time To Be Invested

- Photo 1+2: 10 ETCS = 300h
- Semester = 13 weeks of teaching
- Photo 1:  $3VL + 2Ü = 62.5\%$
- Photo 2:  $2VL + 1Ü = 37.5\%$

## Calculation

- Exam preparation: 60h (240h remain)
- Photo 1:  $240h * 62.5\% = 150h$
- Photo 2:  $240h * 37.5\% = 90h$
- **Photo 2:**  $90h/13 \text{ weeks} = \mathbf{7h/week}$

# Tutorials



Louis Wiesmann



# Module Exam

- Written exam at the end of the winter term after the Photo II course
- Exam admission (Studienleistung)
  - 50% of the points from the homework assignments of Photo I
  - 50% of the points from the homework assignments of Photo II

# Homework Assignments

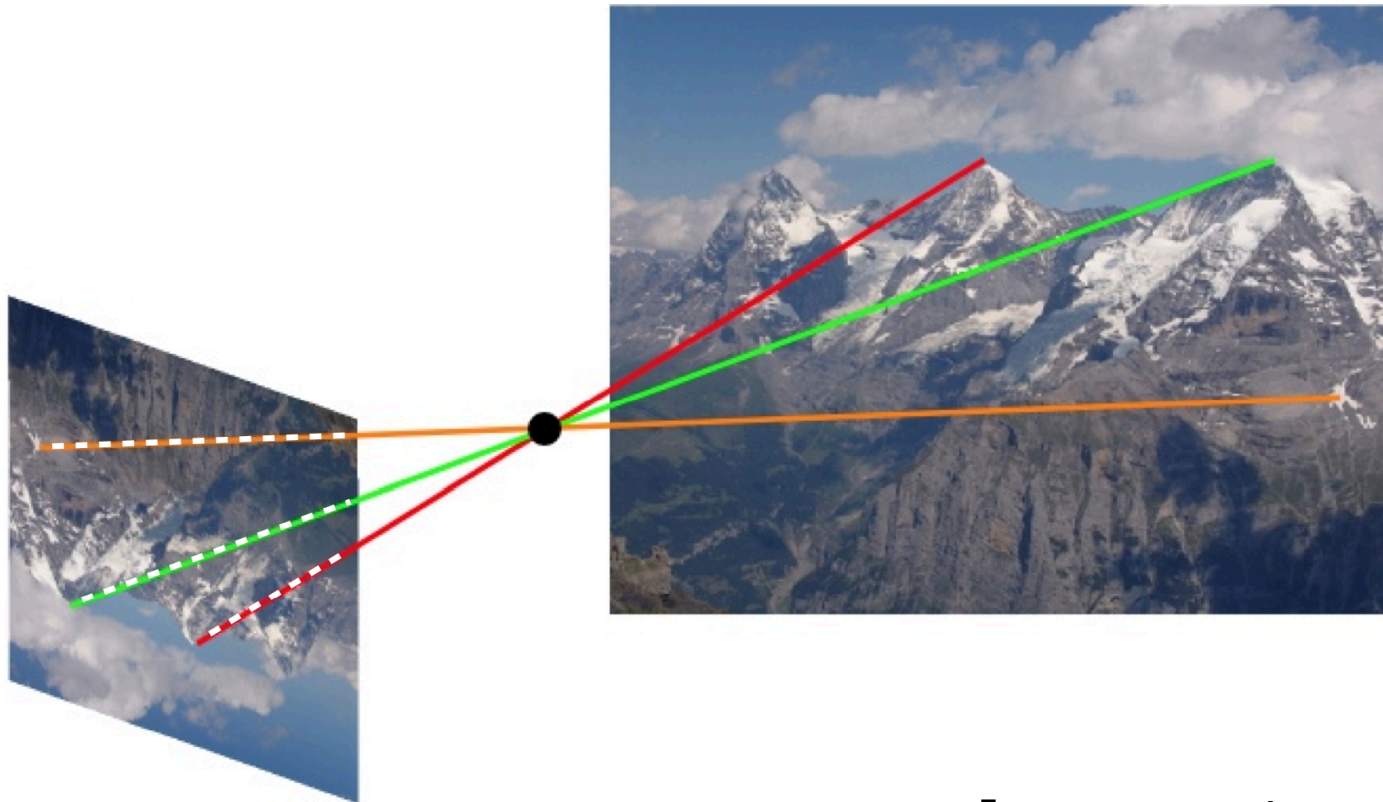
- Submission in groups of **2 students**
- **Limit** the collaboration between groups
- Assignment and submission via eCampus
- **50%** of the points of the homework assignments for exam admission

# **Zero Tolerance on Plagiarism**

# **Photogrammetry II – Topics**

# Cameras to Measure Directions

An image point in a camera image defines a ray to the object point



# 3D Perception

Multiple observations from different directions allows for estimating the 3D location of points via triangulation

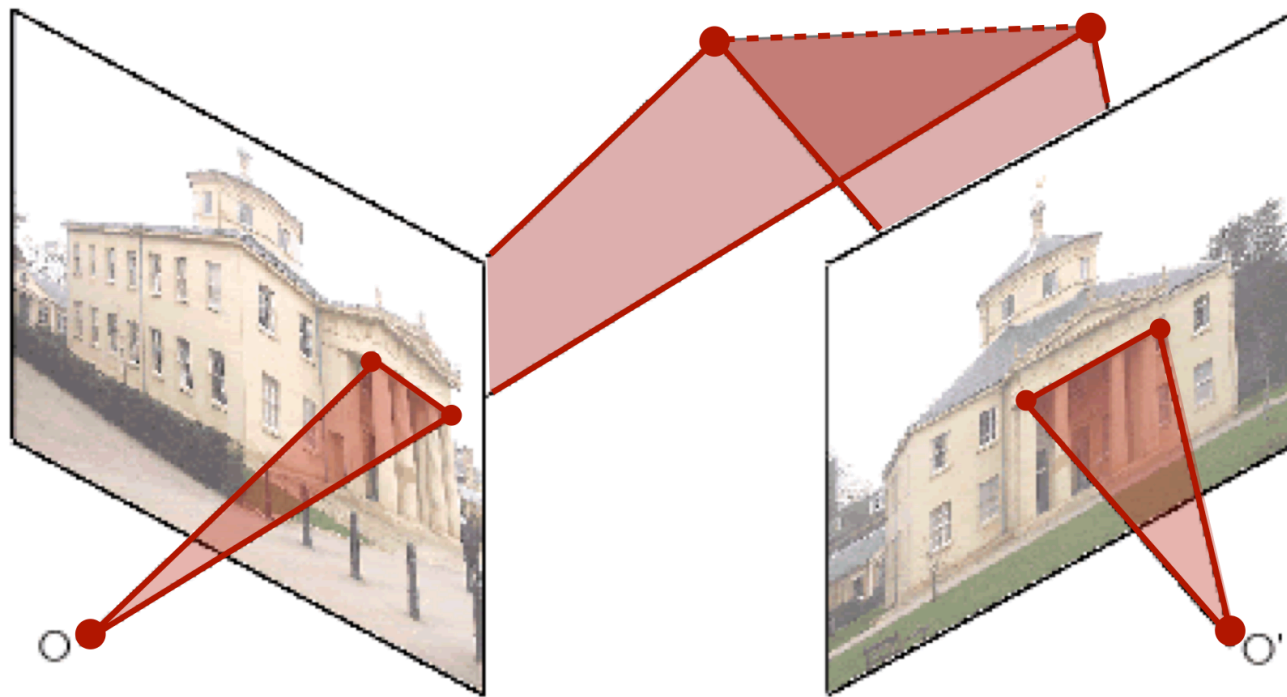
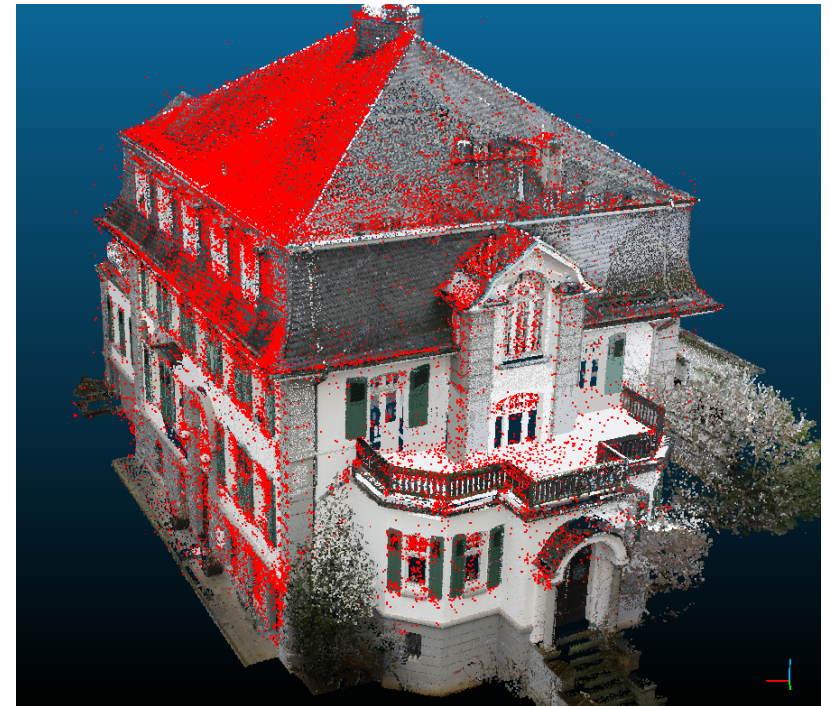
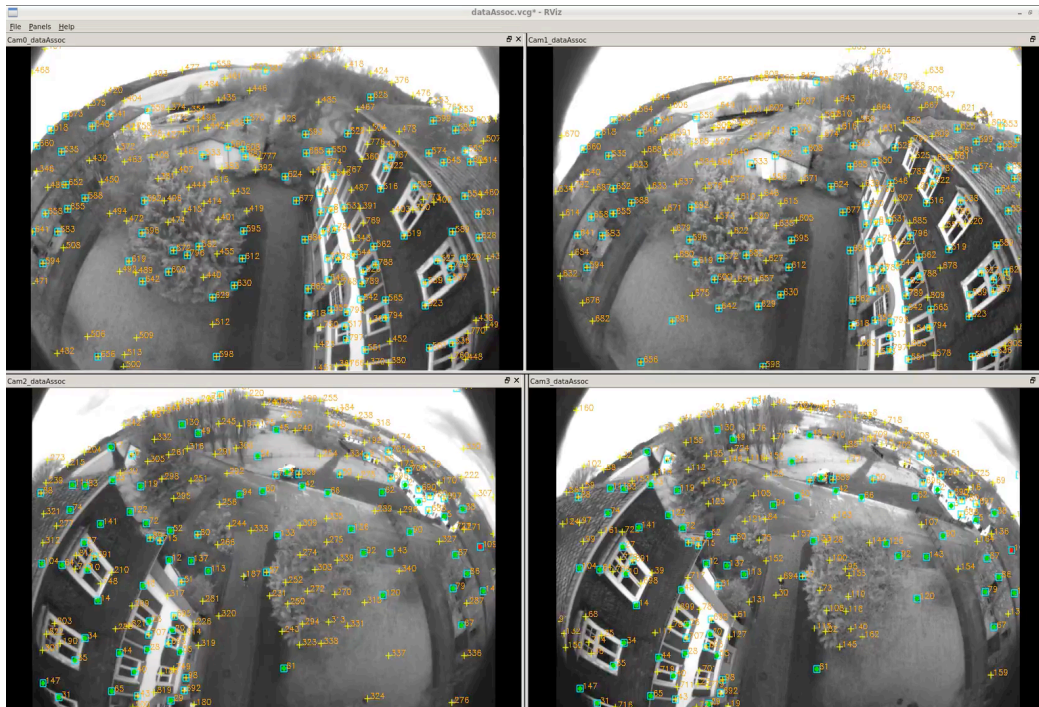


Image courtesy: Schindler 10

# Camera Pose and Point Cloud Estimation





# Orthophotos





# Photo II: Stereo and Multi-Image Photogrammetry

- Relative orientation of two cameras
- Direct and iterative RO methods
- Triangulation
- Bundle Adjustment
- Orthophotos
- Correspondences & RANSAC
- Recursive state estimation (KF, EKF, UKF)
- Simultaneous localization and mapping

# Literature

- **Förstner, Photogrammetrie II**
- **Förstner & Wrobel: Photogrammetric Computer Vision, 2015**
- **Thrun, Burgard, Fox: Probabilistic Robotics, 2005**
- Szeliski: Computer Vision: Algorithms and Applications. Springer, 2010
- Hartley & Zisserman: Multiple View Geometry in Computer Vision, 2004

**Questions?**